

# IROS Best Paper Award on Mobile Manipulation Finalists Sponsored by OMRON Sinic X Corp.

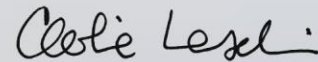
**A Novel Variable Stiffness Suspension System for Improved Stability  
and Control of Tactile Mobile Manipulators**

\*Mehmet Can Yildirim, Sebastian Kuhn, Edmundo Pozo Fortunić,  
Kübra Karacan, Abdalla Swikir, Sami Haddadin

This certificate is presented to promote the research on mobile manipulation



**JORGE MANUEL MIRANDA DIAS**  
GENERAL CHAIR



**CECILIA LASCHI**  
PROGRAM CHAIR